# Python DMRS library: pydmrs

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# GraphLang

#### A DMRS graph description language



proper\_q --> named(Kim) <-1- \_eat\_v\_1 -2-> \_cake\_n\_1 <-- udef\_q

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## Motivation:

- Succinct and easily read-/writeable representation for DMRS
- DMRS formalism similar to MRS formalisms like Oepen et al. (2004)
- Useful if one wants to quickly specify a DMRS graph, e.g. for debugging

# GraphLang

#### A DMRS graph description language



proper\_q --> subj:named(Kim) x[3s\_+\_] <-1- \_like\_v\_1 e[ppi--]; :\_like\_v\_1 -2h-> \_eat\_v\_1 e[pui--] -2-> \_cake\_n\_1 x[3s\_\_\_] <-- udef\_q; :\_eat\_v\_1 -1-> :subj

## Features:

- Sortinfo syntax (short form): e[pui--], textttx[3s\_\_\_]
- Node identifier via colon prefix: subj:named
- Referring back to nodes via leading colon: :\_like\_v\_1, :subj

## Matching & mapping Search



node <-1- \_eat\_v\_1 e? -2-> \_?obj\_n\_1 x?

## Features:

- Underspecification of nodes or parts of their properties
- Identifier suffix for querying

# Matching & mapping



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## Query tool:

# Matching & mapping

Replace



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Node identifier (with square brackets) for mapping alignment

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#### Paraphrase tool:

> python3 paraphrase.py paraphrases.txt "Kim likes to eat cake." Kim eats cake.

# More specialised concepts

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**Subgraph node:** "Kim eats apple cake."  $\rightarrow$  "What does Kim eat?"

Search: \*[1]:\_v e[p????] -2-> {2}:node

Replace: \*[1]:\_v e[q???] -2-> [2]:thing x <-- which\_q

# More specialised concepts

**Equality constraint:** "I think I will go."  $\rightarrow$  "I am thinking of going."

- Search: [1]:node=1 <-1- [2]:\_think\_v\_1 e[????-] -2h-> [3]:\_v e[pfi--]; :3 -1-> node=1
- Replace: [1]:node <-1- [2]:\_think\_v\_of e[????+] -2-> nominalization x; udef\_q --> :nominalization =1h=> [3]:\_v e[pui-+]

# Applications

- Robust text query, e.g. for ontology extraction from WikiWoods
- Paraphrasing (examples in pydmrs)
- Sentence simplification/normalisation
- Machine translation, similar to the MRS transfer formalism of e.g. Bond et al. (2011) or Oepen et al. (2004)
- Mapping between graph formalisms or to/from simplified "DMRS graphs", e.g. Guy's robot language
- Other ideas?